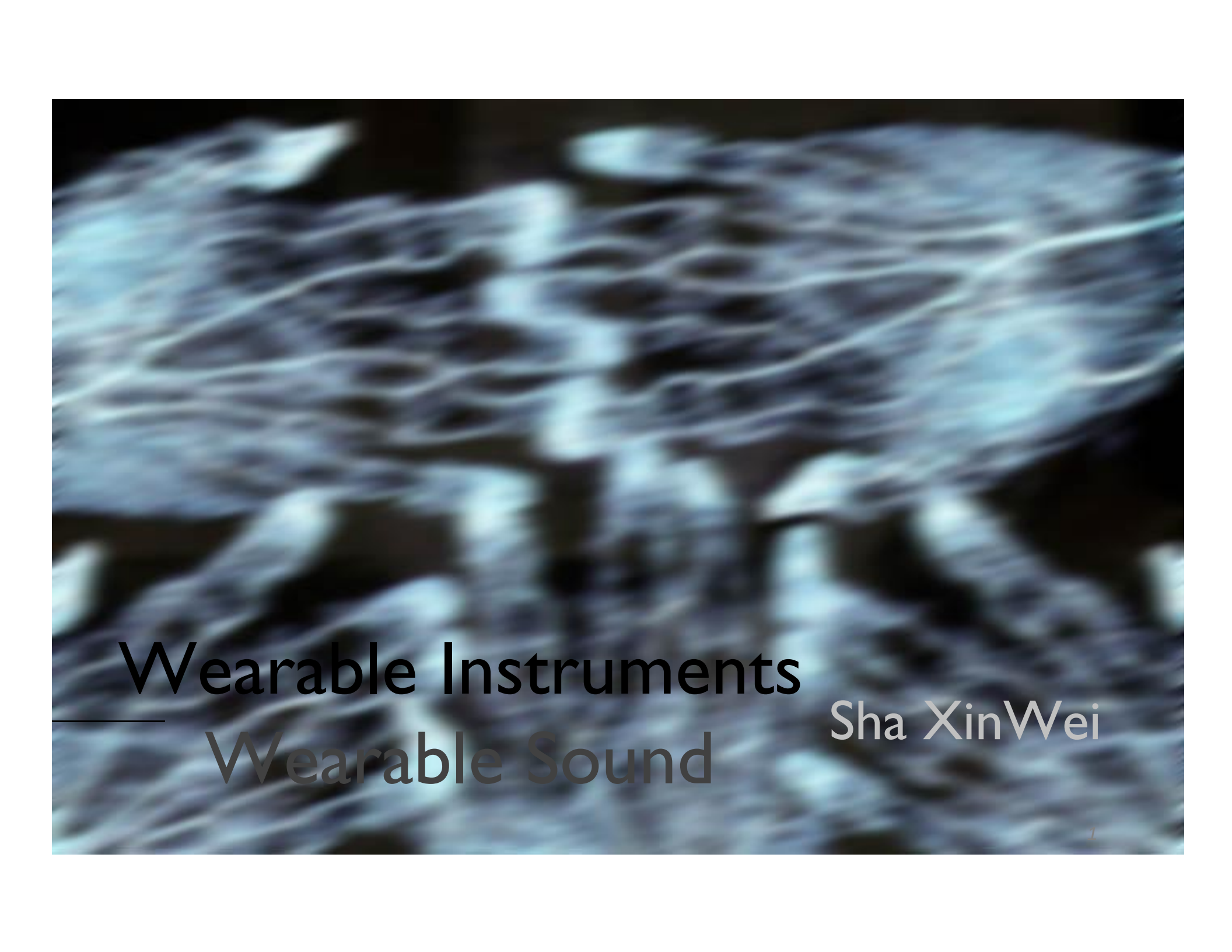
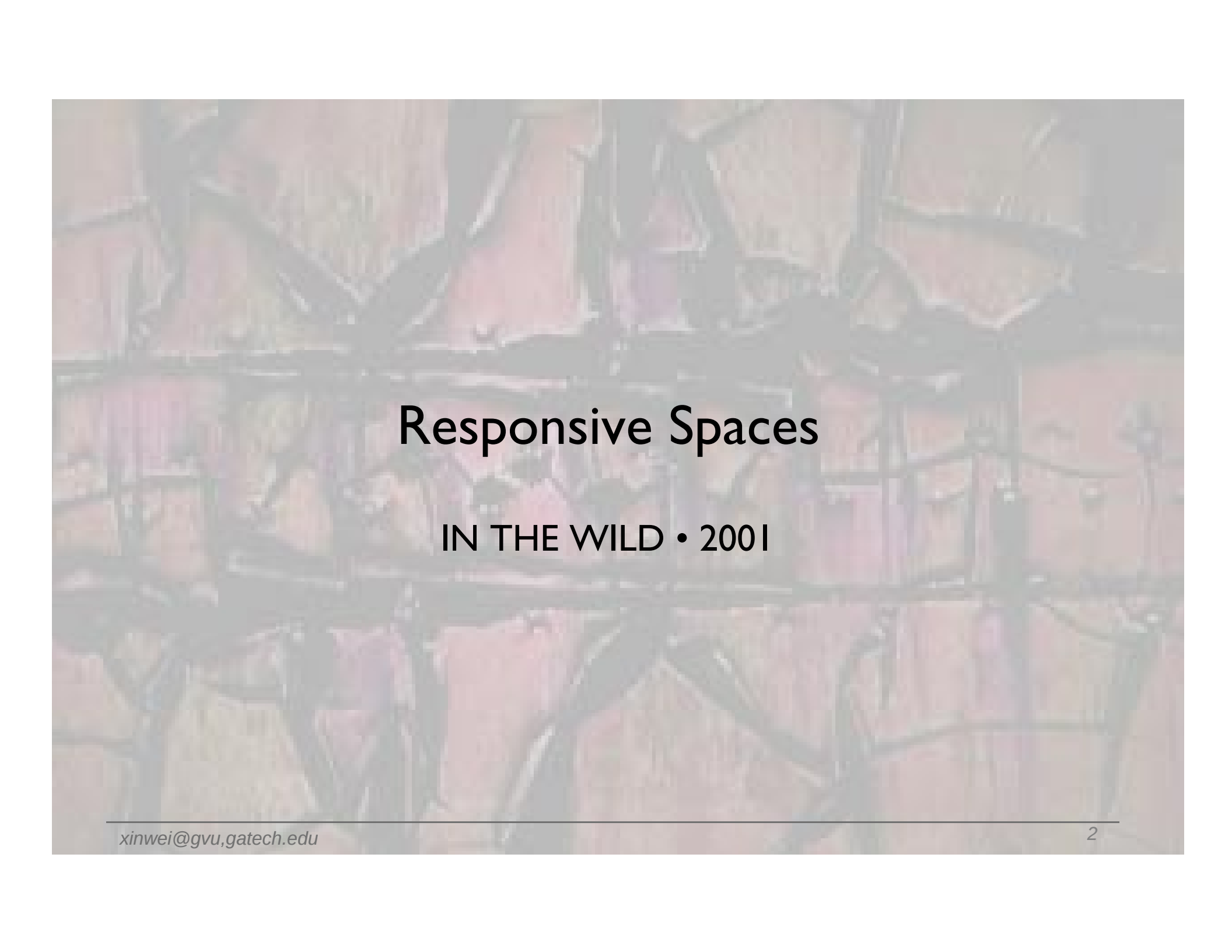


The background of the slide is a dynamic, abstract pattern of glowing blue and white lines that flow and swirl across a dark, almost black, field. These lines vary in thickness and brightness, creating a sense of movement and depth, reminiscent of light trails or fluid motion.

Wearable Instruments

Wearable Sound

Sha XinWei



Responsive Spaces

IN THE WILD • 2001

Thick in-vivo Experiments

In a continuous, responsive, dense, living space –

How do we coordinate action without explicit language?

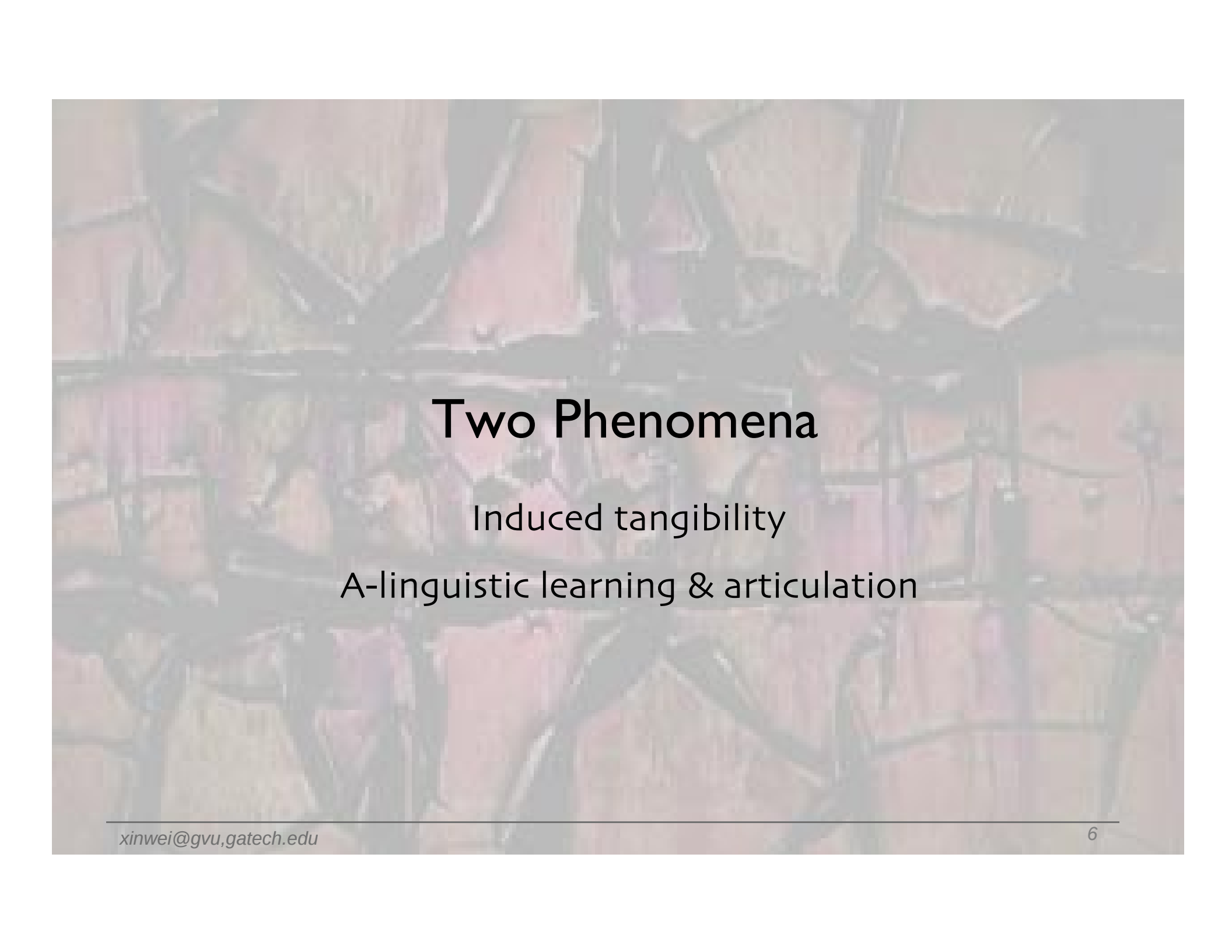
How do we improvise gestures ?

What makes something palpable ?

How we become more adept playing ? Virtuosity.



Staging



Two Phenomena

Induced tangibility

A-linguistic learning & articulation

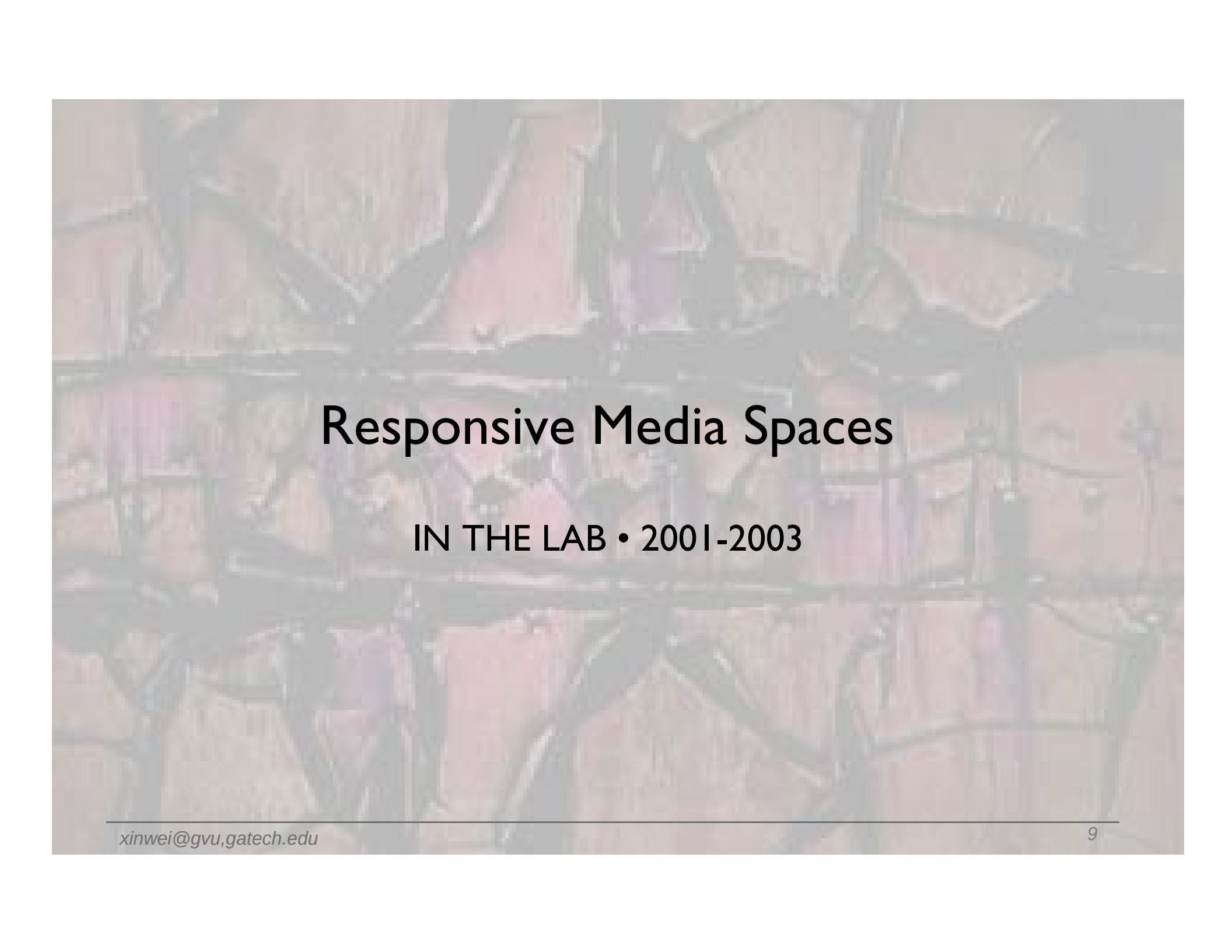
Induced tangibility



(play hopskip) Ars Electronica 2001

Discovery & Improvisation





Responsive Media Spaces

IN THE LAB • 2001-2003

Blair MacIntyre

Erik Conrad

Junko Tsumuji

James Hsu

Yon Visell

Kat Tejavaniya

Jehan Moghazy

David Demumbrum

Jim Ransone

Yoichiro Serita

Yvonne Caravia

Sunderesan Jayaraman

Sungmee Park

Wolfgang Reitberger

Vinny Fiano ...

*

Topological Media Lab

School of Literature, Communication and Culture

New Media Center

Graphics and Visualization Lab

Georgia Institute of Technology

Topological Media Lab

Gesture & Materiality

micro Hybrid computational / physical material

Tangibility and materiality

Temporal textures

Gesture

Domestic spaces

Design and inhabit rich, responsive, dense media

macro Urban spaces

Wearable Computing

Body-borne and Environmental Sensors

Wireless

TinyOS, motes (UC Berkeley, Intel; Dey, Paulos)

Active Fabrics, Softwear

Softwear collaborations (Jayaraman, Park; Tejavaniya;
Berzowska)

Applied Pattern/Signal Analysis

Vision tracking

Gesture tracking

Speech tracking



Media Choreography

Realtime video and sound synthesis

Responsive Media Authoring Systems

Continuous Time State-Evolution

Media Choreography

STATE SPACE

scratch

home base

magnetic field

fat

solated skin

sneaky surfaces

KNEAD STRETCH

DISTORT

CURVE STRETCH

hurling

convective

bubbling lava

move

blow

digesting

eating

Vomiting Monsters

foddy

Octopus

mud

pressure

MOUTH

DEEP

SPAWN

BIRTH/DEATH

MONSTER

SPRAY

LIT OF ALL ISWELL

DYNAMIC

into room

infinite

thick

traces

SCRATCH SCALP

and

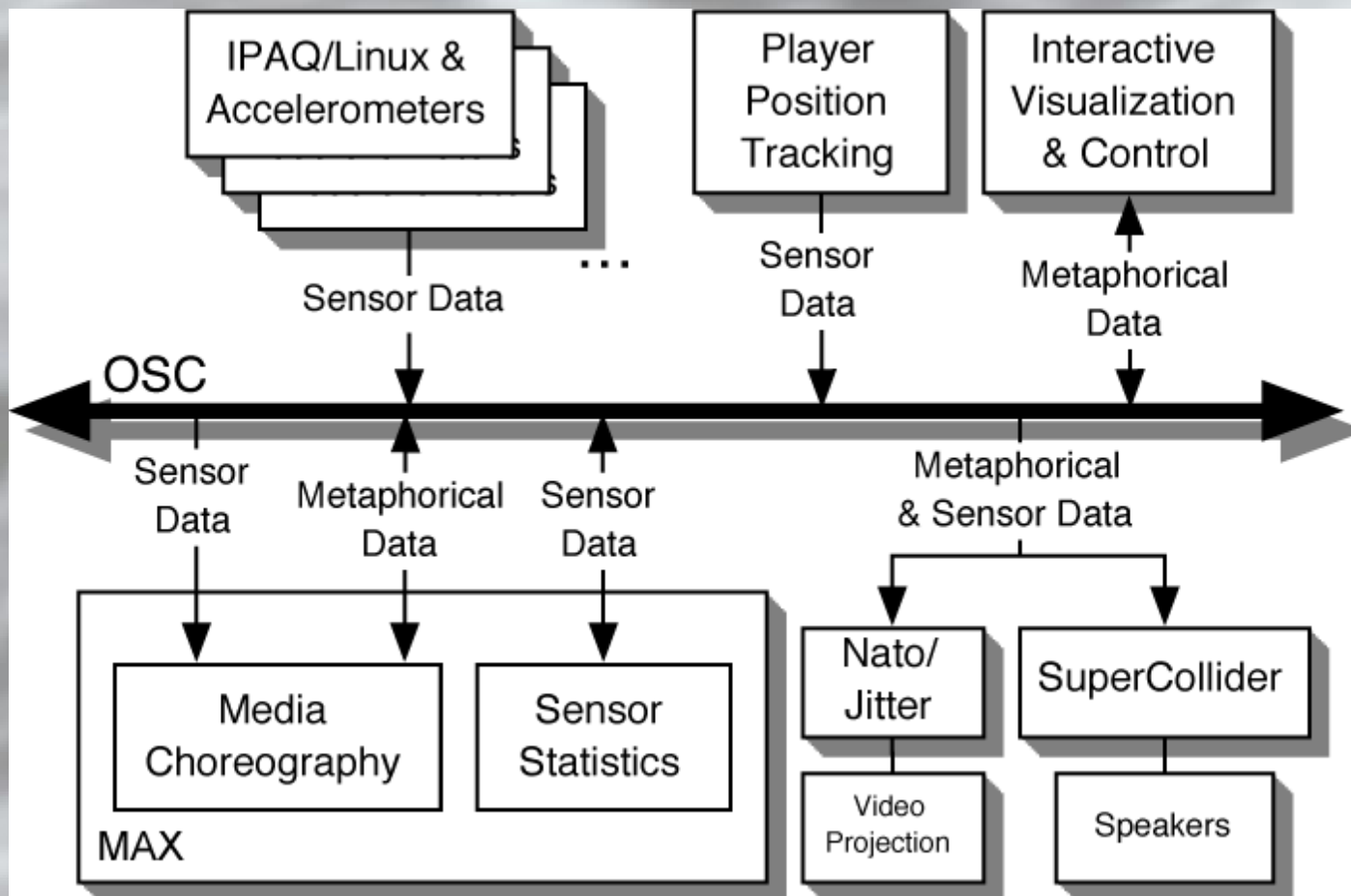
dynamic

and

Substrate "physics" (proto-narrative)

Substrate “physics” (proto-narrative)

Architecture



Statistics

“Intention” and “Learning”

Preliminaries

Calibration (accelerometers and IR)

Data throttling

Scalar vs 1d or 2d array

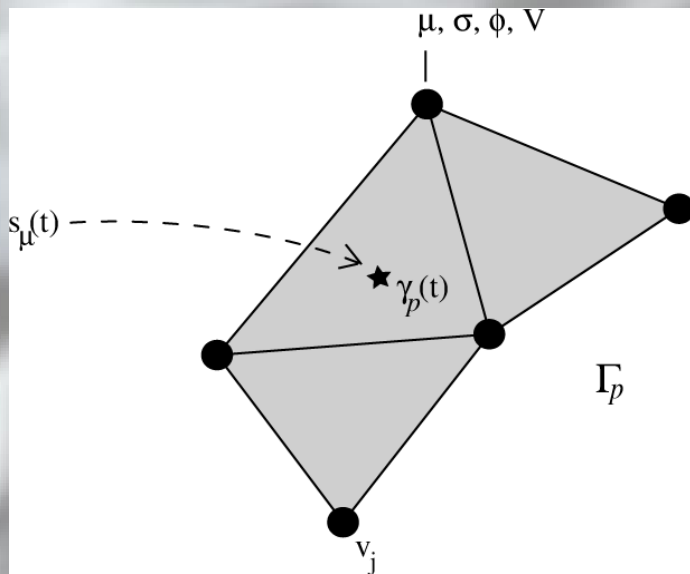
Instantaneous or integral

Integration over time or sample

Application: Leaky accumulator for slewing

Dynamical System on Simplicial Complex

Statistical Physics



States Manifold: meaningful experience, as metaphors

State: (convex) combination of pure states

Potential energy $U = E(\text{sensor}) + E(\text{static})$

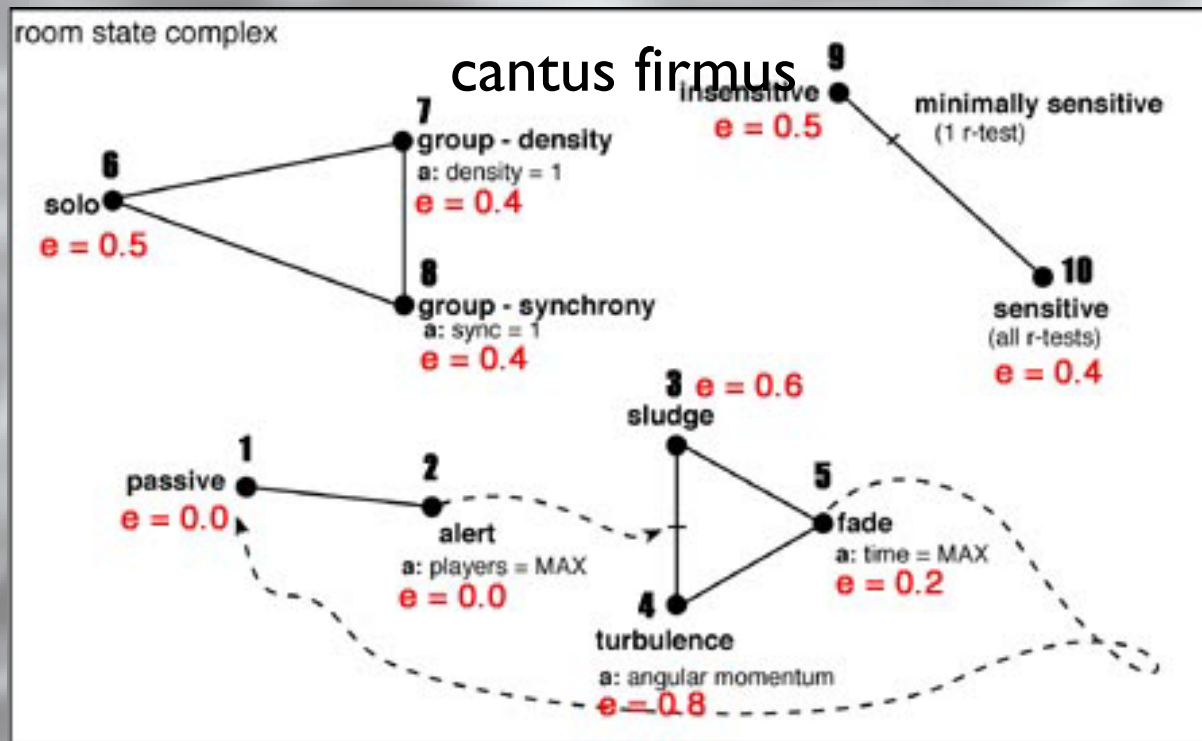
Kinetics: $F = -\text{Grad}[U]$

Arnold, Classical Mechanics

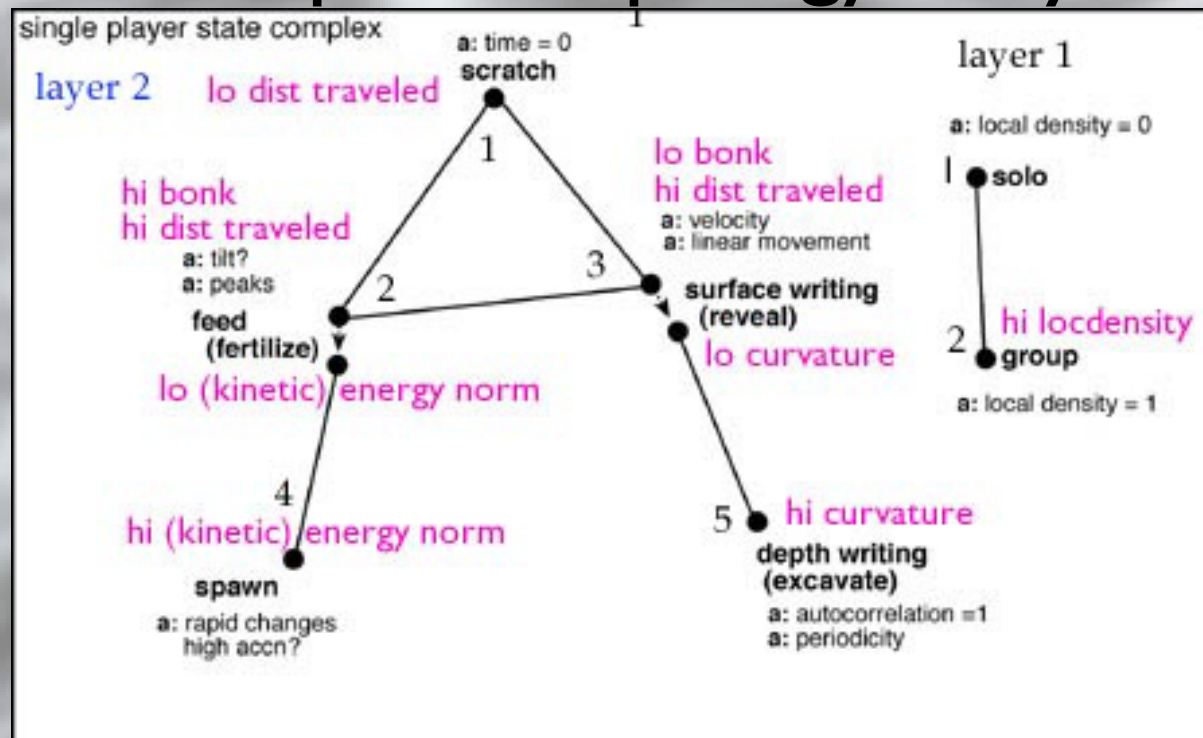
Itzykson & Drouffe, Statistical Field Theory

Jordan, Learning in Graphical Models

Phase Space Topology: Room



Phase Space Topology: Player



Dynamical System Overview

Total manifold = Metaphorical State x Observables

$$M = \prod_{p=0}^{N_p} M_p = \prod_{p=0}^{N_p} \Gamma_p \times S_p.$$

$$\gamma_p(t) = \sum_{j=1}^N \lambda_j(t) v_j \quad \sum_{j=1}^N \lambda_j(t) \equiv 1 .$$

Energetic Model

$$U[\gamma_p(t)] = \sum_{v_i \in \sigma(\gamma_p(t))} f(\lambda_i) \left\{ e^{-\beta E_k[s_{\alpha,p}(t)] + g_s \phi_k} + g_V V_k \right\}$$

$$E_k[s_{\alpha,p}(t)] = \sum_{\alpha\beta=1}^{N_s} (\mu_{\alpha k} - s_{\alpha,p}(t)) (\mu_{k\beta} - s_{\beta,p}(t)) / \sigma_{\alpha\beta}$$

Dynamics

$$F[\gamma_p(t)] = -\nabla U - \xi \dot{\gamma}_p(t)$$

In convex coordinates

$$F_k = \frac{-dU}{d\lambda_k} - \xi \dot{\lambda}_k$$

Discrete states and discrete transitions are special case
Good framework to handle noise, hysteresis.

Equation of Motion

∇U on phase space

The evolution is given by

$$\dot{x}_m \rightarrow \dot{x}_m + \frac{1}{m} F_m^t \, dt$$

$$x_m \rightarrow x_m + \dot{x}_m \, dt$$

where

dt = integration timestep

m = mass of particle

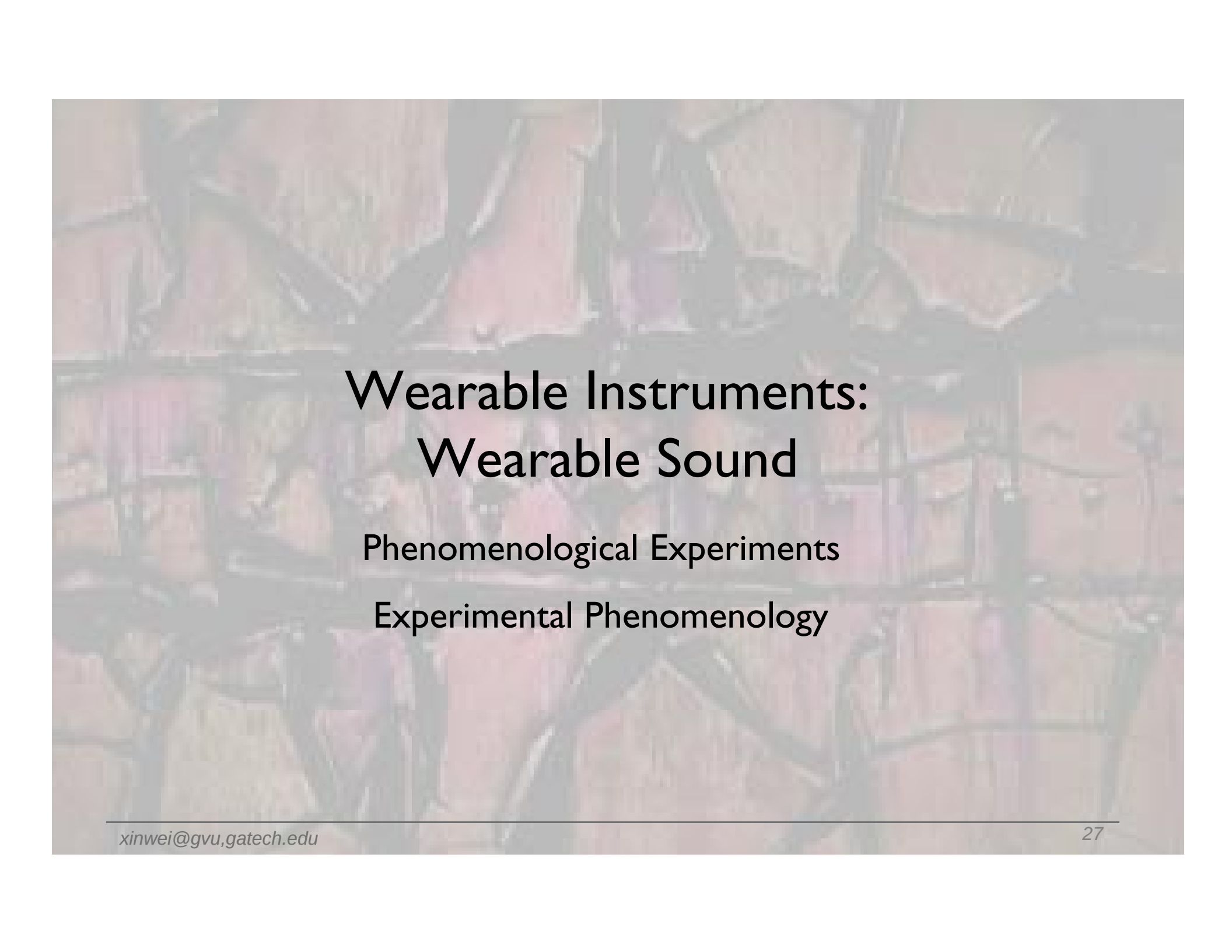
Calligraphic Video May 2002



Resonance Response May 2002



Spectral
Methods
(Kac)



Wearable Instruments: Wearable Sound

Phenomenological Experiments

Experimental Phenomenology

Softwear: Body + Garment

Matter, Poetry and Poiesis

Patterns: tattoos, (virus), resonance

Gesture instrument

Material as memory, amplification

Thick space

Fabric Media



S. Jayaraman and S. Park @ Georgia Tech

J. Berzowska; E. Kusaite, M. Kuzmanovic et al.; S. Diamond et al.

K. Tejavaniya, Y. Caravia, J. Fantauzza @ TML

Research Agenda

Experimental

Gesture, Movement

Tracking, Feature Extraction

Continuous Media Choreography

Softwear, Wireless Sensors, Fabric

Design

Realtime Video Synthesis

Realtime Sound Synthesis

Applications

Softwear: wearable sound

Responsive Media Spaces